

The Open University of Sri Lanka
 B.Sc. / B.Ed. Degree Programme – Level 05
 Final Examination -2013/2014
 Applied Mathematics
 APU3240/APE5240 – Numerical Methods



Duration: Three Hours

Date: 09. 06. 2014

Time: 01.00 p.m. – 04.00 p.m.

Answer Five Questions Only.

1. (a) Briefly explain simple iterative method.
 - (b) Let $x = \xi$ be a root of $f(x) = 0$ such that $\xi \in I$ where I is an interval. Let $\phi(x) - x \equiv f(x)$ such that $\phi(x)$ and $\phi'(x)$ be continuous in I . Prove that if $|\phi'(x)| < 1$ for all $x \in I$ the sequence x_1, x_2, \dots, x_n defined by $\phi(x_n) = x_n$ converges to the root ξ provided that initial approximation $x_0 \in I$.
 - (c) Using simple iterative method, find the root of the equation $\sin x - 3x + 1 = 0$ lying in the interval $[0, 0.5]$ and correct to four decimal places.
2. (a) Prove that

(i) $E = \Delta + 1,$	(ii) $E = (1 - \nabla)^{-1},$	(iii) $\delta = E^{1/2} - E^{-1/2},$
(iv) $\mu = \frac{1}{2}(E^{1/2} - E^{-1/2}),$	(v) $\mu\delta = \frac{\Delta + \nabla}{2},$	
- where $\Delta, \nabla, \delta, \mu$ and E are the forward difference, the backward difference, the central difference, the average and the shift operators respectively.
- (b) Derive the Gregory- Newton backward interpolation formula. Hence, interpolate $f(42)$ corresponding to the data points (20, 354), (25, 332), (30, 291), (35, 260), (40, 231) and (45, 204).

3. (a) Show that cubic spline interpolation polynomial that passes through the points $(x_0, y_0), (x_1, y_1), \dots, (x_n, y_n)$ is given by

$$M_{i-1} + 4M_i + M_{i+1} = \frac{6}{h^2}(y_{i-1} - 2y_i + y_{i+1}).$$

- (b) Find the cubic splines interpolation polynomial that passes through the points $(1, 1), (2, 2), (3, 5)$ and $(4, 11)$.
4. (a) Evaluate the integral $\int_0^1 \frac{x^2}{1+x^3} dx$, using Simpson's One third rule, by dividing the interval into 4 equal parts.
- (b) Find the Lagrange polynomial (f) passing through the points $(-1, -1), (-2, -9), (2, 11)$ $(4, 69)$ and determine $f(0)$.

5. (a) (i) Derive formula for the Picard's method to solve $\frac{dy}{dx} = f(x, y)$ subject to the initial condition $y(x_0) = y_0$.
- (ii) Using Picard's method, find the first-three successive approximations to solve $\frac{dy}{dx} = 1 + xy$ with the initial condition $y(0) = 1$.
- (b) (i) Derive formula for the modified Euler's method to solve $\frac{dy}{dx} = f(x, y)$ subject to the initial condition $y(x_0) = y_0$.
- (ii) Solve $\frac{dy}{dx} = x + y$ with the initial condition $y(0) = 0$ using the modified Euler's method, at $x = 0.6, x = 0.8$ and $x = 1.0$.

6. (a) State fourth order Runge-Kutta algorithm to solve $\frac{dy}{dx} = f(x, y)$ subject to the initial condition $y(x_0) = y_0$.
- (b) Using fourth order Runge-Kutta method, solve $\frac{dy}{dx} = xy + y^2$ with the initial condition $y(0) = 1$ at $x = 0.1$ and $x = 0.2$.
- (c) Solve $\frac{d^2y}{dx^2} + x\frac{dy}{dx} + y = 0$, with the initial condition $y(0) = 1$, $y'(0) = 5$, using fourth order Runge-Kutta method at $x = 0.1$.
7. (a) State Milne's Predictor – Corrector Method to solve $\frac{dy}{dx} = f(x, y)$ subject to the initial condition $y(x_0) = y_0$.
- (b) Solve $\frac{dy}{dx} = x(x^2 + y^2)e^{-x}$, $y(0) = 1$, by Taylor series method for $x = 0.1, 0.2, 0.3$ and hence find $y(0.4)$ by Milne's Predictor – Corrector Method.
8. (a) State Adam-Bashforth Predictor – Corrector Method to solve $\frac{dy}{dx} = f(x, y)$ subject to the initial condition $y(x_0) = y_0$.
- (b) Solve $\frac{dy}{dx} = y - \frac{2x}{y}$, $y(0) = 1$, by Taylor series method for $x = 0.1, 0.2, 0.3$ and hence find $y(0.4)$ by Adam-Bashforth Predictor – Corrector Method.