

The Open University of Sri Lanka

Faculty of Engineering Technology



Study Programme	: Bachelor of Technology (Engineering)
Name of the Examination	: Final Examination
Course Code and Title	: MEX6272 Intelligent Control
Academic Year	: 2013/2014
Date	: 15 th of August 2014
Time	: 9.30am – 12.30 pm
Duration	: 3 hours

General instructions

1. Read all instructions carefully before answering the questions.
2. This question paper consists of 6 questions.
3. Question 1 is compulsory. Answer any three from questions 2 to 6.

Q1.

a) (25 marks)

Consider the fuzzy controller design of a washing machine to automate the *wash time*. The fuzzy logic system need to process the two inputs for the system that are **Dirt(D)** and **Grease(G)** of the clothes to be washed. A fuzzy logic control system will process these, giving a single output, **Wash time(T)**.

The following fuzzy quantities are defined, with the corresponding states:

D: Dirt (SD: Small Dirt, MD: Medium Dirt, LD: Large Dirt)

G: Grease (NG: No Grease, MG: Medium Grease, LG: Large Grease)

T: Wash Time (VS: Very Short, S: Short, M: Medium, L: Long, VL: Very Long)

The membership functions of these quantities are given in Figure Q1.a

The rule base is given in Table 1 as follows:

		Grease		
		NG	MG	LG
Dirt	SD	VS	M	L
	MD	S	M	L
	LD	M	L	VL

Table Q1

At a given instant, the following set of sensor data is available:

- **Dirt– 60**
- **Grease– 75**

- i. List the Linguistic variables and Linguistic values of this fuzzy system.
- ii. Write down rules that would **fire** for the given instance.
- iii. Determine the corresponding inference membership function for the **Wash Time**.
- iv. Determine the crisp value for the control action.

(Hint: Use Max-Min inference method and Centroid method as applicable.)

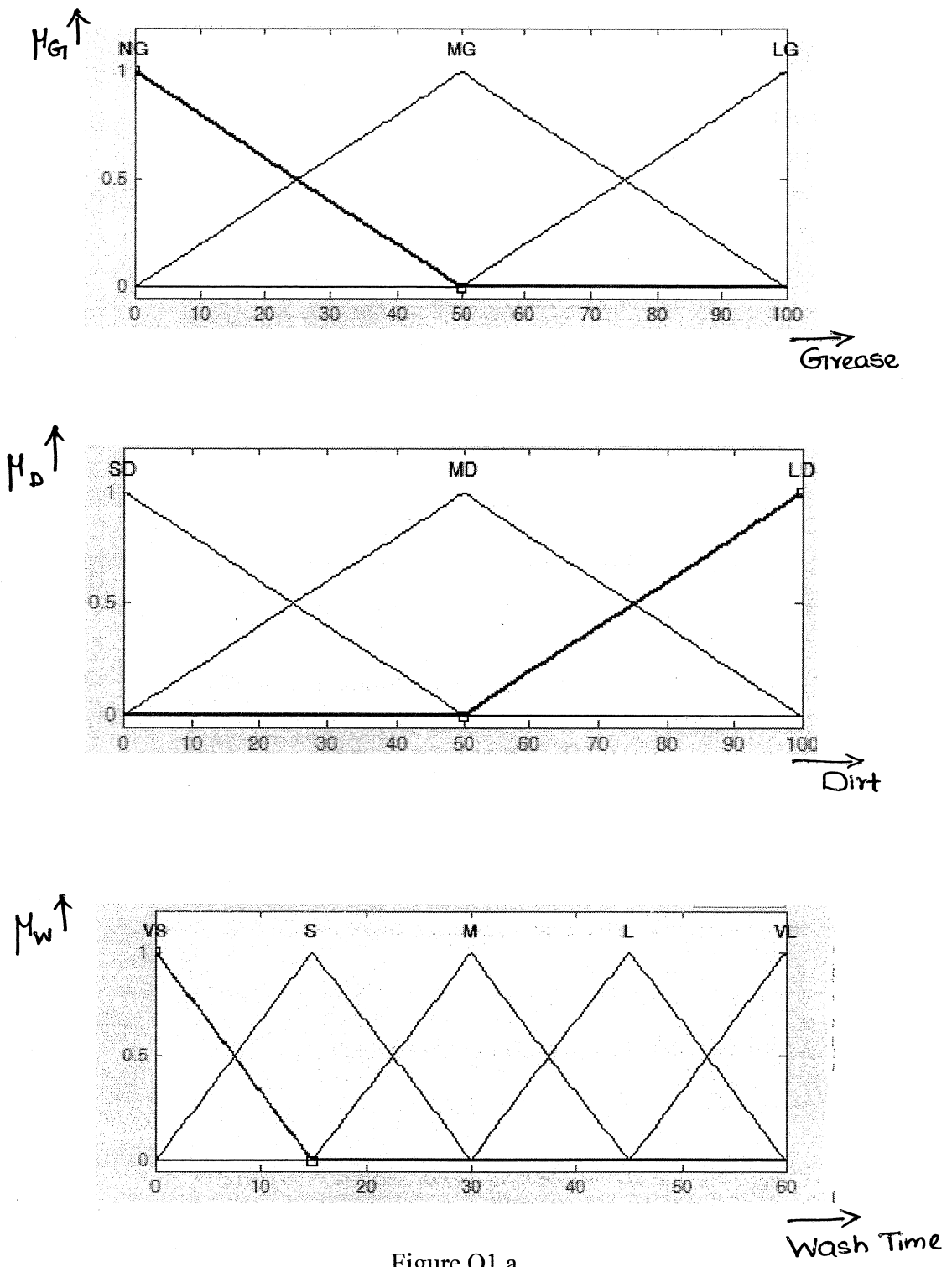


Figure Q1.a

b)

(15 marks)

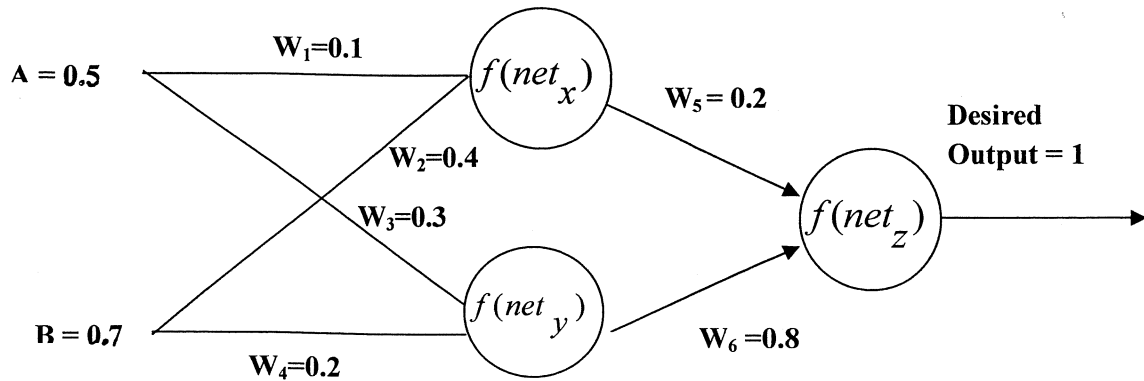


Figure Q1.b

Assume that the neurons have a Bipolar continuous activation function and that $\lambda = 1$ and $\eta = 1$. Use Backpropagation method to find the old and new errors of the trained network.

Use the standard error finding method to find the error.

$$[\text{Error} = \text{Output}(1-\text{Output})(\text{Target}-\text{Output})]$$

Q2.

(20 marks)

a) Consider a first order fuzzy dynamic system whose free (unforced; input = 0) response is given by

$$X_{j+1} = X_j \circ R$$

Where

X_j = discrete membership function of the j^{th} fuzzy state transition.

R = matrix representing the fuzzy rule base relation of state transition.

Find whether the fuzzy systems are stable or not for the following cases.

- i. $R = \begin{bmatrix} 0.5 & 0.4 \\ 0.4 & 0.5 \end{bmatrix}$
- ii. $R = \begin{bmatrix} 0.4 & 0.4 \\ 0.5 & 0.4 \end{bmatrix}$

b) A fuzzy system is represented by

P^1 : If $x(k)$ is A^1 then $x^1(k+1) = 1.2x(k) - 0.6x(k-1)$

P^2 : If $x(k)$ is A^2 then $x^2(k+1) = x(k) - 0.4x(k-1)$

Where A^i , $i=1,2$ are shown in the Figure Q2. Check if the system is stable by

Lyapunov's method if the positive definite matrix is $P = \begin{bmatrix} 2 & -1.2 \\ -1.2 & 1 \end{bmatrix}$.

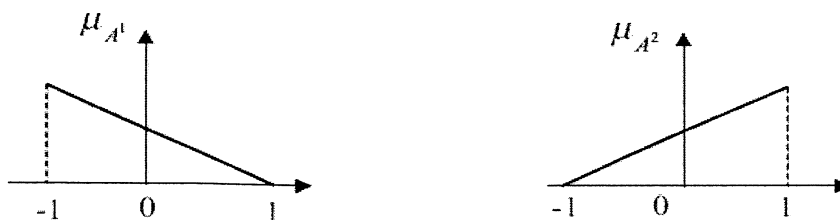


Figure Q2

Q3.

(20 marks)

- a) Let $U=\{a, b, c, d\}$ be the domain and A and B be fuzzy sets on U as given on the Table Q3.

	a	b	c	d
A	0.5	0.8	0.0	0.3
B	0.2	1.0	1.0	0.7

Table Q3

Proof the following property of fuzzy sets A and B which is known as De Morgan's law $(A \cup B)^1 = A^1 \cap B^1$ considering the above values.

- b) Consider the ternary fuzzy relation T on $U \times V \times W$, where $U=\{a,b\}$, $V=\{x,y\}$ and $W=\{\&,*\}$ are fuzzy sets;

$$T = \frac{0.1}{(a, x, \&)} + \frac{0.8}{(b, x, \&)} + \frac{0.5}{(a, y, \&)} + \frac{0.9}{(a, y, *)} + \frac{0.2}{(b, y, *)}$$

- i. Find T_1 and T_2
 - ii. Find T_{12}
- c) The logical implication in the linguistic rule form: *if A then B*, can be translated into a relation R using the Cartesian products sets A and B as $R = (A \times B) \cup (\bar{A} \times Y)$.

Let the two universes of discourse be described by $X=\{1,2,3,4\}$ and $Y=\{1,2,3,4,5,6\}$. If the crisp set A is defined as $A=\{1,4\}$ on X and B is defined as $B=\{1,3,5,6\}$ on Y.

Determine the deductive inference IF A, THEN B.

Q4.

(20 marks)

- a) Draw a suitable diagram to show the main components of an **artificial neuron**.
- b) The "glass data set" is a famous dataset that has been used in pattern recognition. A neural network can be built to predict the type of the glass (window glass or non-window glass) based on the measurements of the chemical content. The data set consists of 214 samples.

Attribute information:

Refractive index
Sodium
Magnesium
Aluminum
Silicon
Potassium
Calcium
Barium
Iron

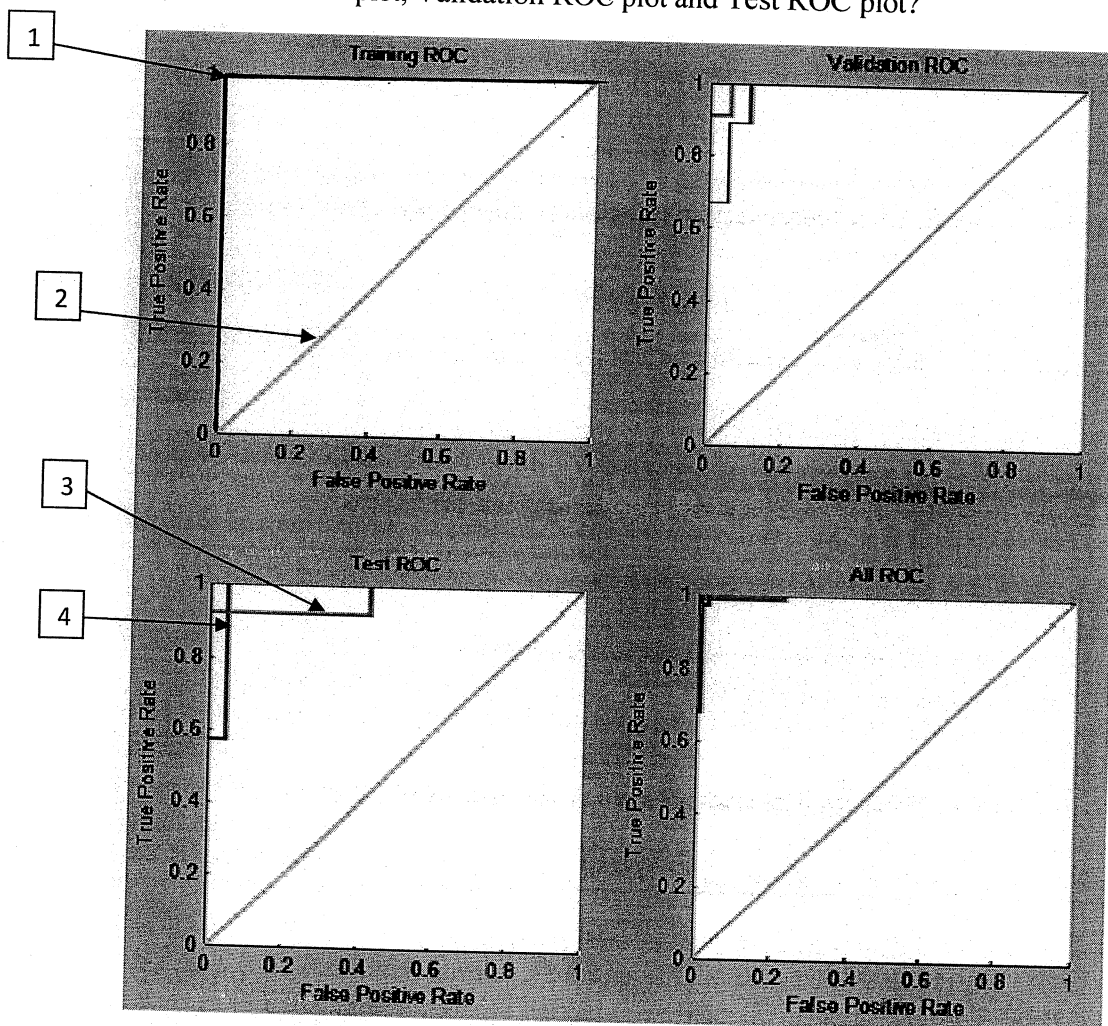
State the following with **reasons** for the neural network that you propose for the glass classification.

- i. Number of input nodes
 - ii. Number of hidden layers
 - iii. Number of output nodes
- c) Compare and contrast Hebbian and Delta training rules considering neural networks.
- d) Briefly discuss the difference between Binary and Continuous Activation functions.
- e) Back Propagation Algorithm is an example of Supervised Learning method. Comment on this statement.

Q5.

(20 marks)

- a) Draw the complete architecture of a Fuzzy logic controller. Name all parts of it and **using suitable examples** describe their functionalities.
- b) Figure Q5 shows a ROC (Receiver Operating Characteristic) plot obtained after training an ANN (Artificial Neural Network) using MATLAB software. Answer the following questions considering Figure Q5.
- i. What does a ROC curve demonstrate?
 - ii. What comment can you make about the Training ROC plot.
 - iii. Indicate the number of the worst classifier. (Please select a number from 1 to 4 according to the labels)
 - iv. What is the reason to consider three different ROC plots as Training ROC plot, Validation ROC plot and Test ROC plot?



Q6.

(20 marks)

- a) Briefly explain an application of *Genetic Algorithm*.
- b) List two characteristics of *intelligence* and state whether they are applicable for ANN.
- c) Name the suitable *AI technique* to use for each application given below.
 - i. Medical diagnosis system
 - ii. Signature recognition system
 - iii. Autonomous underwater vehicle control system
- d) Discuss the characteristics of intelligent machines.
- e) What are the main components of an expert system?

END